



# ABSTRACT OF THE DISCLOSURE

A switch-off box for a robot system has a two-part housing and a coupling device resiliently mounted in the housing and connected to a torch body and a hose pack or to a torch handle connected with the hose pack, and having a supporting surface for punctual contact on the housing. There are contacting or switching elements connected to the coupling device. Two oppositely located openings are provided in the housing for connection of the coupling device to the torch body and for connection of the coupling device to the hose pack or the torch handle. The supporting surface is connected with the contacting or switching elements so that a respective contacting or switching element will be activated or deactivated by lifting of the supporting surface from the housing, and a signal will be transmitted from the contacting or switching element to an interfaced control device, or the robot system.